

Block ES04 (Eastern South 04)

GRAV-D Airborne Data Release User Manual

Applies to Data BETA Release, 9/2014

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Introduction to GRAV-D and Data User Manuals

NOAA's National Geodetic Survey (NGS) launched the Gravity for the Redefinition of the American Vertical Datum (GRAV-D) program in 2007. This program is designed to replace the current national vertical datum (NAVD 88) with a datum based upon a gravimetric geoid by 2022. To produce the geoid with 1-2 cm accuracy (where possible), an airborne campaign has been launched to measure the gravity field over all of the US and its holdings.

A more comprehensive description of the GRAV-D project is available in the "GRAV-D General Airborne Gravity Data User Manual." The version of that manual that applies to this release is manual v. 2.X. That manual also describes general details of the nominal airborne field operations, data post-processing software specifics, data naming schemes and distribution, data formats, and how to calculate other commonly-used gravity values from the released data. This manual relates details for this block of data that are in addition to the General User Manual.

GRAV-D uses some specific terminology (e.g. "block" for a geographic area with enough flown data and tie lines to provide error statistics, and "survey" for an occupation by the field team of a particular airport, at a particular time, and with a particular aircraft and instrument suite). For a full list of terminology, refer to the Glossary in the Appendices of the "GRAV-D General Airborne Gravity Data User Manual."

Contents

Introduction to GRAV-D and Data User Manuals	1
Figure List	3
Table List	3
1. Block Description	4
2. Survey Design and Execution	5
2.1 GPS/IMU Instrumentation	7
2.2 Gravity Instrumentation	7
3. GPS and Gravity Data Processing	8
3.1 Whole-Survey Applicable Details	8
3.1.1 GPS	8
3.1.2 Ground Gravity Tie	8
3.1.3 Gravity Filtering	9
3.2 Whole-Block Applicable Details	9
3.2.1 Gravity Error Analysis	9
3.3 Flight- and Line-Specific Details	11
3.3.1 GPS processing- by flight	11
3.3.2 Gravity processing- by line	12
4. Data Usage Guidelines	20
4.1 Suggested Data Handling	20
4.2 Documentation	20
4.3 How to Cite These Data	20
5. References	20

Figure List

Figure 1: Google Earth Image of the Location of Block ES04	4
Figure 2: Data Coverage for ES04.....	6
Figure 3: Crossover Residuals, Histogram, and Statistics for Block ES04.	10
Figure 4: Full-field gravity at altitude (mean removed) for Block ES04.	18
Figure 5: Free-air gravity disturbance for Block ES04 with respect to the WGS-84 ellipsoid. ...	19

Table List

Table 1: Latitude and Longitude Coordinates of Corner Points Defining Block ES04.....	4
Table 2: Survey Overview	5
Table 3: Aircraft and Instrumentation	5
Table 4: Survey Design and Execution	5
Table 5: Lever Arm Measurements FROM the Center of the Gravimeter's Sensor TO the Other Instruments	7
Table 6: Lever Arm Measurements FROM the SPAN TO the GPS Antenna	7
Table 7: GPS High Rate Data Availability (1 Hz or higher).....	8
Table 8: Gravity Crossover Error Analysis	9
Table 9: Quality of Cross Lines Used in Crossover Analysis.....	11
Table 10: Average Data Line Correlation.....	11
Table 11: GPS+IMU and GPS-only Kinematic Processing Results.....	12
Table 12: Gravity Processing Results.....	14
Table 13: Bias from EGM08 by Line	16

1. Block Description

GRAV-D Block **ES04** is located in the **E**astern Time Zone, in the **S**outh half (south of 40° latitude). This was the fourth (**04**) block of data completed in that region. Block ES04 is about 600 km by 360 km over the east coast, including North Carolina, Virginia, and South Carolina ([Figure 1](#)). The corner coordinates defining Block ES04 are listed in [Table 1](#).

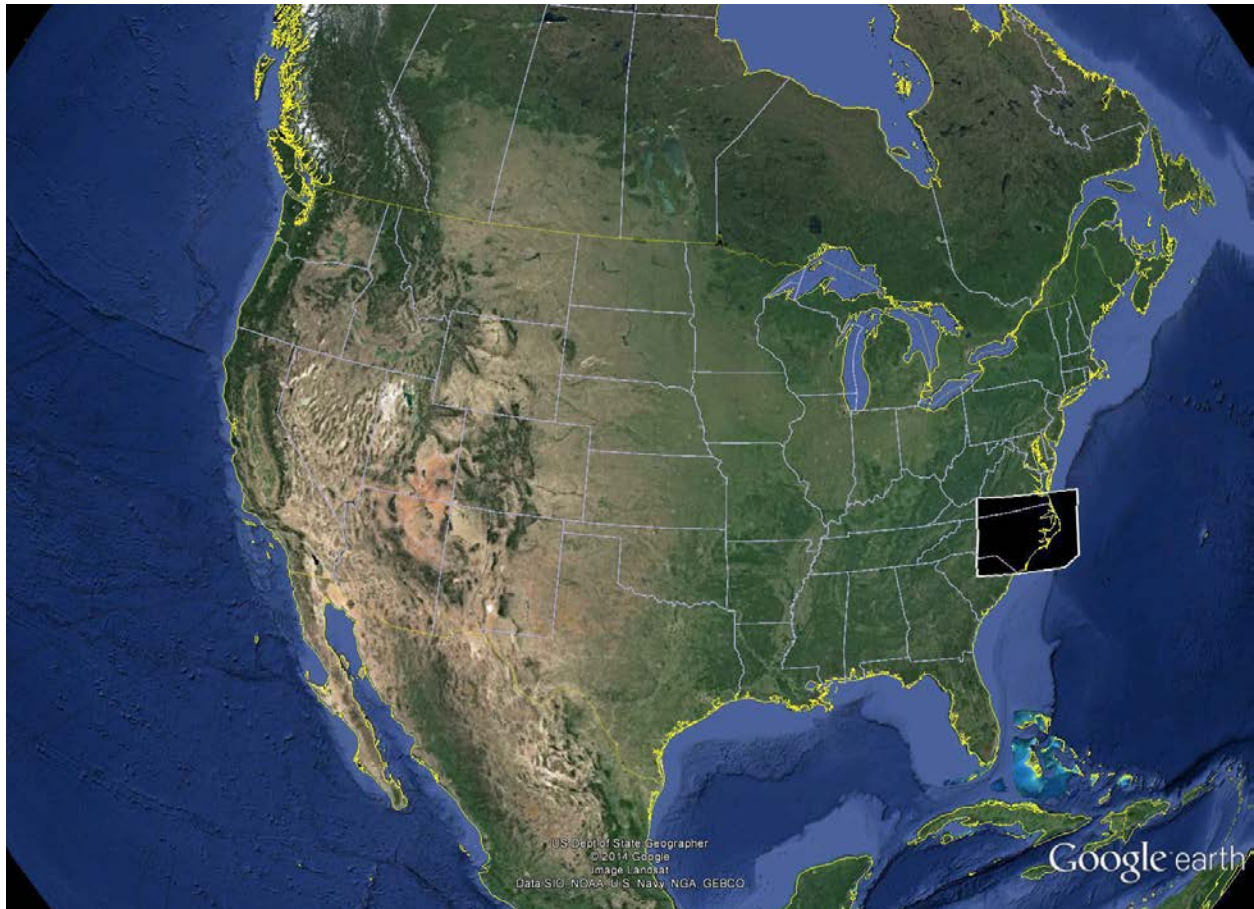


Figure 1: Google Earth Image of the Location of Block ES04.

Table 1: Latitude and Longitude Coordinates of Corner Points Defining Block ES04

Latitude (decimal degrees)	Longitude (decimal degrees)
-80.954979684	34.015051265
-75.463097587	33.460374923
-74.448262400	33.864882423
-73.897478631	36.802227221
-80.512823753	37.407060306

2. Survey Design and Execution

Airborne gravity data in Block ES04 were collected during two surveys: NC13 (North Carolina 2013) & NC14 (North Carolina 2014). All data and cross flights were done at 17,500 ft with the same aircraft and instrument suite. [Table 2](#), [Table 3](#), and [Table 4](#) give a synopsis of survey layout and execution for the data. [Figure 2](#) shows the data coverage, plotted in Google Earth.

In the ES04 all data lines are East-West and cross lines North-South. The block consists of 52 data lines, 9 cross lines. Because of aircraft and weather challenges this block had many reflights. To reduce confusion the acceptable lines released here were renumbered such that the lines labeled in the 200s and 600s are the second part of the corresponding 100s or 500s line respectively (i.e. 101 and 201 would be two parts of the same planned data line). In the data file, line numbers are preceded by the block name (i.e. ES04101= block ES04's line 101).

Table 2: Survey Overview

Conducting Organization	NOAA- National Geodetic Survey Fugro Earth Data, Inc.	
Survey Name	NC13	NC14
Airport Base of Operations	Smith Reynolds Airport (INT) Winston-Salem, NC FBO: Landmark Aviation	
Geographic Location	Mid-Atlantic	
Dates of Airborne Operations	Nov 18 th 2013-March 11 th 2014	June 9 th -August 19 th 2014

Table 3: Aircraft and Instrumentation

Aircraft	Cessna 441 Conquest II	Hawker Beechcraft King Air E90A
Engines, number and type	2, Turboprop	2, Turboprop
Gravity Instrumentation	Micro-g LaCoste (MGL) TAGS S-160 (relative) MGL A-10 25 (absolute) MGL D-43, G-6 (relative)	Micro-g LaCoste (MGL) TAGS S-161 (relative) MGL A-10 25 (absolute) MGL D-43, G-6 (relative)
GPS Instrumentation	NovAtel DL-4 Plus NovAtel SPAN-SE (GPS + IMU)	

Table 4: Survey Design and Execution

Line Spacing	Data Lines: 10 km Cross Lines: ~40 km
Type of Layout	Regular data lines & regular cross lines
Nominal Survey Altitude	17,500
Nominal Aircraft Ground Speed	250 knots
Number of Lines Released	Data Lines: 52 Cross Lines: 9 Repeat Lines: 0
Number of Crossovers	231

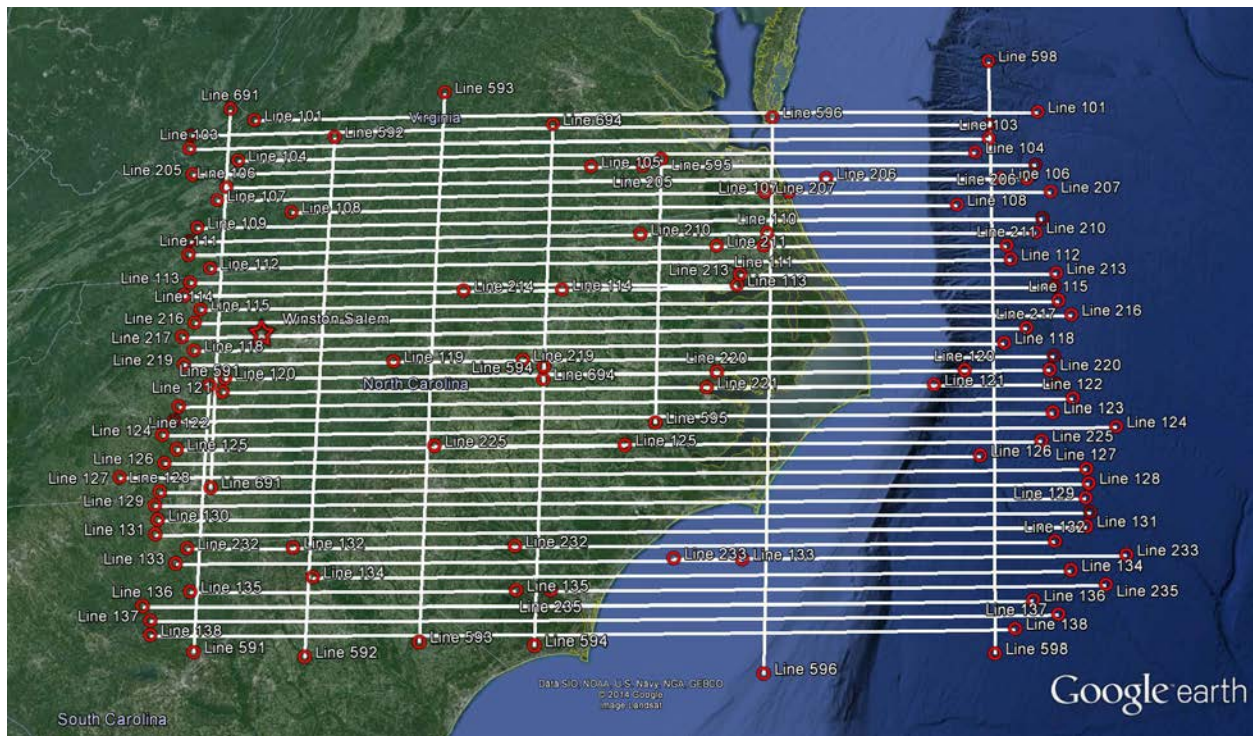


Figure 2: Data Coverage for ES04. Data lines start in the north at 101 and continue south to 138. Airports marked with red star.

2.1 GPS/IMU Instrumentation

The Cessna 441 Conquest II and Hawker Beechcraft King Air each had one GPS antennas available for scientific measurements. Two geodetic-quality GPS receivers shared the antenna: NovAtel DL-4 Plus (included as part of the TAGS gravimeter timing unit) and a NovAtel (inside the SPAN-SE system). The NovAtels had a data rate of 1 Hz and the SPAN NovAtel of 20Hz. The NovAtel μ IMU system also contained an Inertial Measurement Unit (IMU) that recorded aircraft orientation information at 200 Hz during the flight, including pitch, roll, yaw, and heading.

On the ground, two Ashtech Z-Surveyors recorded at 1 Hz and served as GPS base stations throughout the survey. See Section [3.2.1](#) for a table of GPS data available for each flight and processing details.

2.2 Gravity Instrumentation

The Micro-g LaCoste TAGS (Turn-key Airborne Gravimetry System) was mounted in the cargo area. The TAGS records data at 1Hz and has a NovAtel timing unit mounted on the gravimeter. The gravimeter also records an environmental file at 0.1 Hz. For more information on the instrument, refer to its user manual (Micro-g LaCoste, 2010).

The IMU was mounted on top of the TAGS and in the center of the frame. [Table 5](#) lists the lever arm measurements between the TAGS and other instruments (distances are measured along the body of the aircraft: X positive toward the nose, Y positive toward the right, and Z positive down.) [Table 6](#) lists the lever arm measurement between the TAGS and the SPAN-SE (distances measured along the body of the aircraft: X positive toward the right, Y positive toward the nose, and Z positive up).

Table 5: Lever Arm Measurements FROM the Center of the Gravimeter's Sensor TO the Other Instruments

Instrument/Location	X (m)	Y (m)	Z (m)
NovAtel SPAN-SE IMU	-0.017	0.019	-0.433

Table 6: Lever Arm Measurements FROM the SPAN TO the GPS Antenna

Instrument/Location	X (m)	Y (m)	Z (m)
GPS Antenna (Conquest II)	0.025	-0.75	0.481
GPS Antenna (King Air)	-0.135	-0.34	0.606

3. GPS and Gravity Data Processing

3.1 Whole-Survey Applicable Details

3.1.1 GPS

Table 7: GPS High Rate Data Availability (1 Hz or higher)

Airport	Type	Receiver	Flight Available	2013-2014 Day of Year Available
INT (NC13)	Kinematic	NovAtel (0002)	F01, F03, F06, F11, F13-F16, F18-F19, F21-F30	322-324, 335-337, 354, 12-13, 59-61, 65, 57, 69-70
		NovAtel (SPAN)	F01, F03, F06, F11, F13-F16, F18-F19, F21-F30	322-324, 335-337, 354, 12-13, 59-61, 65, 57, 69-70
	Static	Ashtech 3552	F01, F03, F06, F11, F13-F16, F18-F19, F21-F30	322-324, 335-337, 354, 12-13, 59-61, 65, 57, 69-70
		Ashtech Noth	F01, F03, F06, F11, F13-F16, F18-F19, F21-F30	322-324, 335-337, 354, 12-13, 59-61, 65, 57, 69-70
INT (NC14)	Kinematic	NovAtel (0002)	F01, F03, F05, F09, F13, F15-F16, F18-F29	160, 164, 166, 175, 183, 186-187, 194-195, 199, 208, 211, 219-220, 226-228, 230-231
		NovAtel (SPAN)	F01, F03, F05, F09, F13, F15-F16, F18-F29	160, 164, 166, 175, 183, 186-187, 194-195, 199, 208, 211, 219-220, 226-228, 230-231
	Static	Ashtech 3552	F01, F05, F09, F13, F15-F16, F20-F29	160, 166, 175, 183, 186-187, 199, 208, 211, 219-220, 226-228, 230-231
		Ashtech Noth	F01, F05, F09, F13, F15-F16, F18-F29	160, 166, 175, 183, 186-187, 194-195, 199, 208, 211, 219-220, 226-228, 230-231

Data were processed using WGS84 and ITRF08. Average position accuracy for the data block is calculated from the final GPS position solution. Position standard deviation is estimated by the GPS processing programs for each flight and those numbers are averaged to provide a survey-wide estimate of GPS position accuracy. For the data lines, the average horizontal position accuracy is 0.008 m and the average vertical position accuracy is 0.011 m.

3.1.2 Ground Gravity Tie

Absolute gravity measurements were performed by NGS with a Micro-g LaCoste A-10 gravimeter in July 2013. The A-10 was set up at the exact location of the aircraft. The positions were determined from the GPS collected during the gravity survey while the plane was parked. In Winston-Salem, NC the location is designated as KINT TAGS (36.148635478°N ,

80.224701494°W) and it has an absolute gravity value of 979703.17697 ± 0.0077 mGal at 146.6 cm above the tarmac.

3.1.3 Gravity Filtering

Newton v1.2 uses a time-domain Gaussian filter that is applied three times to the data during final filtering. The Gaussian filter chosen for this survey has a 6-sigma of 120s, i.e. a 2-sigma of only 40s. Applying the filter three times provides superior noise reduction compared to a single application of the filter. Although the triple application provides better noise reduction, the filter is tailored to best preserve the amplitudes of the long wavelength signal, while allowing some short wavelength noise to remain in the final product. For suggestions on data handling, including on further noise suppression, see Section [4.1 Suggested Data Handling](#).

3.2 Whole-Block Applicable Details

3.2.1 Gravity Error Analysis

Crossover error analysis was done by identifying the crossing points of the data lines and cross lines and then applying the standard free-air correction to bring all points to the average altitude of the block. There was an unidentified bias in all flight lines, so an additional correction was applied before the crossover analysis to adjust each line's median airborne gravity value to the median gravity value of EGM08 along the line. The bias-corrected difference between the cross line gravity value and data line gravity value is the residual. The square root of the RMS of the residuals yields the total RMS error. For ES04, the result of the crossover analysis is shown in [Table 8](#) and in [Figure 3](#).

Table 8: Gravity Crossover Error Analysis

Nominal Altitude (ft)	Nominal Altitude (m)	Altitude for Analysis (m)	Number of Crossovers	RMS Of Residuals (mGal)	Std. Dev. Of Residuals (mGal)	Mean Crossover Difference (mgal)	RMS Error (mGal)
17,500	5,334	5,453	231	3.45	3.45	-0.10	2.44

One assumption of crossover analysis is that the quality of the cross lines are high and that the crossover difference reflects only the error in the data lines. This is not necessarily the case. This means that the crossover statistics do not accurately reflect the quality of the data lines, due to the errors in the cross lines. One way to quantify this problem is by reporting the standard deviation and mean of the crossover residuals for each cross line, as in [Table 9](#). The higher the standard deviation of the residuals, the more likely that the cross line was noisy. Also, a non-zero mean could indicate a cross-line bias with respect to the data lines (unlikely here because of the bias correction applied), which would produce false crossover statistics that indicate poor data line quality.

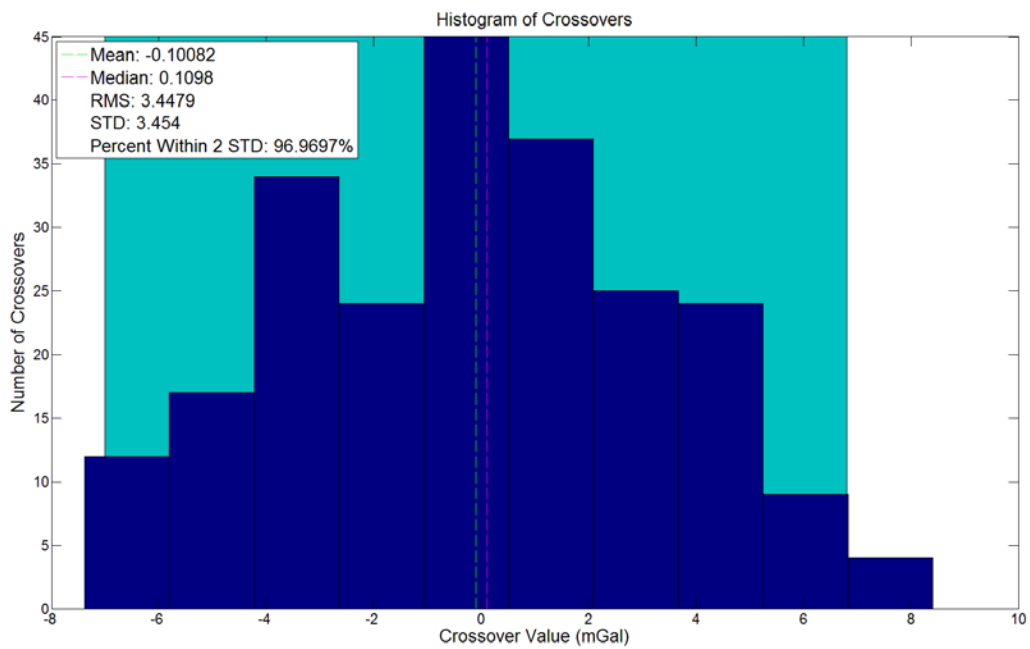
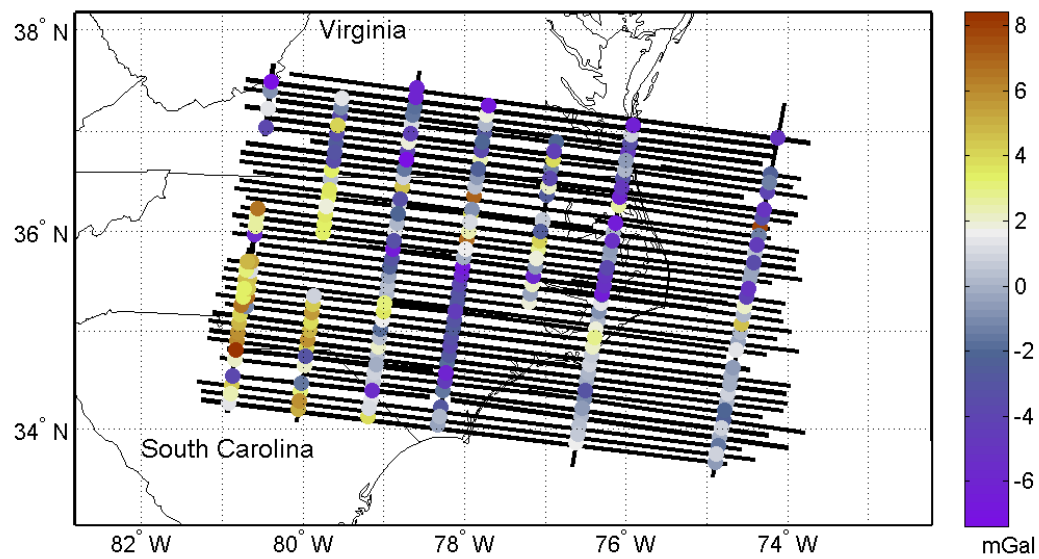


Figure 3: Crossover Residuals, Histogram, and Statistics for Block ES04. Color scale in mGals.

Table 9: Quality of Cross Lines Used in Crossover Analysis

Cross Line Number	Standard Deviation of Residuals Along Line (mGal)	Mean of Residuals Along Line (mGal)
591	2.75	3.86
592	3.16	1.91
593	3.06	-0.78
594	1.77	-3.29
595	2.88	0.00
596	2.91	-1.38
598	2.90	-0.72
691	4.43	1.21
694	3.39	0.63

Another way to evaluate the quality of gravity data is to calculate the correlation of the gravity values along two adjacent data lines. Average correlation and statistics on the spread of correlations can yield information about the quality of the data lines ([Table 10](#)). This technique works well as a measure of data quality in areas with little lateral variability in the gravity field (such as the Gulf of Mexico). But the technique doesn't work well when the correlations are not expected to be high, such as in areas with large changes in topography and/or density from data line to data line. Line correlations were calculated for adjacent lines and then averaged to give an overall quality measurement. Correlations > 80% mean the lines are very highly correlated, 70% - 80% mean the lines are highly correlated, 50% - 70% mean the lines are more correlated than not, and <50% are more uncorrelated than correlated.

Table 10: Average Data Line Correlation

Number of Correlations	Average Data Line Correlation	Standard Deviation of Correlations
42	93.37%	9.55%

A fourth way of gauging data quality is by calculating the repeatability of the gravity signal along reflight lines of good quality. Reflight analysis can also help to pinpoint the lightest filtering that produces highly-correlated results.

3.3 Flight- and Line-Specific Details

3.3.1 GPS processing- by flight

GPS data were processed in Inertial Explorer (IE) 8.5. A lever arm correction (to move the position solution from that of the GPS antenna to that of the center of the gravimeter) was applied within the IE software and included in the GPS+IMU solution. In the case of the GPS-only solution, no IMU data were available and a translation-only, vertical lever arm correction was instead applied by the Newton gravity code to translate the GPS-only positions to the center of the gravimeter.

NGS has developed an independent method of measuring the quality of GPS position solutions based on information available from IE. For the GPS-only part of the position solution, the quality analysis takes into account the following: whether a fixed or float solution was achieved,

the magnitude of the combined separation between forward and reverse solutions (a measure of precision), and the estimated position accuracy. For details on the calculation, please refer to the “GRAV-D General Airborne Gravity Data User Manual.”

3.3.2 Gravity processing- by line

All gravity processing was done with NGS’ Newton v1.2 software. For a description of the package, refer to the “GRAV-D General Airborne Gravity Data User Manual.” The final gravity data file contains full-field gravity at altitude ([Figure 4](#)), although other gravity products such as free-air anomalies or free-air disturbances ([Figure 5](#)) can be easily calculated by following directions in Section 4 of the “GRAV-D General Airborne Gravity Data User Manual”.

Table 11: GPS+IMU and GPS-only Kinematic Processing Results

Survey	Flight Num.	Rover GPS Unit	Solution Type	Elevation Mask (degrees)	Line Num.	NGS Quality Grade
NC13	1	SPAN	GPS+IMU	5	591	83.60
	3	SPAN	GPS+IMU	7.5	594	100.00
	6	SPAN	GPS+IMU	5	135	100.00
	11	SPAN	GPS+IMU	7.5	101	100.00
					102	100.00
	13	SPAN	GPS+IMU	7.5	109	100.00
	14	SPAN	GPS+IMU	5	106	100.00
					107	100.00
	15	SPAN	GPS+IMU	7.5	110	100.00
	16	SPAN	GPS+IMU	5	103	100.00
					104	100.00
	18	SPAN	GPS+IMU	5	592	100.00
	19	SPAN	GPS+IMU	5	115	100.00
					118	100.00
	21	SPAN	GPS+IMU	7.5	113	100.00
	22	SPAN	GPS+IMU	5	111	100.00
	23	SPAN	GPS+IMU	7.5	105	100.00
	24	SPAN	GPS+IMU	5	119	100.00
	25	SPAN	GPS+IMU	7.5	108	100.00
					205	100.00
					207	100.00
	26	SPAN	GPS+IMU	7.5	213	100.00
					219	100.00
	27	SPAN	GPS+IMU	5	210	100.00
					595	100.00
					691	100.00
	28	SPAN	GPS+IMU	7.5	694	100.00
	29	SPAN	GPS+IMU	7.5	120	100.00
					121	100.00
	30	SPAN	GPS+IMU	7.5	132	100.00

NC14	1	SPAN	GPS+IMU	5	112	100.00
	3	SPAN	GPS+IMU	7.5	114	100.00
	5	SPAN	GPS+IMU	5	206	100.00
					211	100.00
					220	100.00
					221	100.00
	9	SPAN	GPS+IMU	6	593	100.00
	13	SPAN	GPS+IMU	5	122	100.00
	15	SPAN	GPS+IMU	7.5	232	100.00
	16	SPAN	GPS+IMU	5	125	100.00
					126	100.00
	18	SPAN	GPS+IMU	7.5	123	100.00
					214	100.00
	19	SPAN	GPS+IMU	7.5	225	100.00
	20	SPAN	GPS+IMU	5	137	100.00
	21	SPAN	GPS+IMU	7.5	136	100.00
	22	SPAN	GPS+IMU	7.5	124	100.00
					127	100.00
	23	SPAN	GPS+IMU	5	596	100.00
					138	100.00
	24	SPAN	GPS+IMU	7.5	216	90.53
					217	100.00
	25	SPAN	GPS+IMU	5	128	100.00
					129	100.00
	26	SPAN	GPS+IMU	5	133	100.00
					134	100.00
	27	SPAN	GPS+IMU	5	130	100.00
					131	100.00
	28	SPAN	GPS+IMU	7.5	235	100.00
					598	100.00
	29	SPAN	GPS+IMU	7.5	233	100.00

Table 12: Gravity Processing Results

Survey	Flight Num.	Line Num.	Times of Deleted Data Section(s)
NC13	1	591	
	3	594	
	6	135	
	11	101	
		102	
	13	109	
	14	106	
		107	
	15	110	
	16	103	
		104	
	18	592	82473-83006
	19	115	
		118	
	21	113	
	22	111	
	23	105	
	24	119	
	25	108	
		205	
		207	
	26	213	
		219	
	27	210	
		595	61549-62129
		691	
	28	694	
	29	120	
		121	
	30	132	
NC14	1	112	114893-115148, 115554-115925
	3	114	
	5	206	
		211	
		220	
		221	
	9	593	
	13	122	
	15	232	25159-25394
	16	125	
		126	
	18	123	
		214	
	19	225	
	20	137	

	21	136	
	22	124	
		127	
	23	596	
		138	
	24	216	
		217	
	25	128	
		129	
	26	133	
		134	
	27	130	
		131	
	28	235	
		598	
	29	233	

Table 13: Bias from EGM08 by Line

Survey	Flight Num.	Line Num.	Bias from EGM08
NC13	1	591	5.59
	3	594	-2.19
	6	135	6.93
	11	101	7.86
		102	10.73
	13	109	5.99
	14	106	4.10
		107	4.33
	15	110	4.13
	16	103	2.14
		104	4.80
	18	592	4.83
	19	115	6.13
		118	4.71
	21	113	3.40
	22	111	3.53
	23	105	4.11
	24	119	4.56
	25	108	4.17
		205	5.56
		207	6.44
	26	213	7.46
		219	6.84
	27	210	6.67
		595	3.75
		691	5.05
	28	694	4.09
	29	120	6.95
		121	5.06
	30	132	4.12
NC14	1	112	-1.85
	3	114	0.38
	5	206	-3.68
		211	-3.43
		220	-1.00
		221	1.36
	9	593	2.60
	13	122	0.46
	15	232	-1.13
	16	125	0.78
		126	-0.65
	18	123	1.39
		214	0.67
	19	225	-0.66
	20	137	-4.30

	21	136	0.80
	22	124	1.33
		127	0.72
	23	596	1.61
		138	0.81
	24	216	1.74
		217	1.38
	25	128	2.03
		129	1.72
	26	133	1.30
		134	0.81
	27	130	0.96
		131	0.79
	28	235	1.16
		598	1.07
	29	233	-0.34

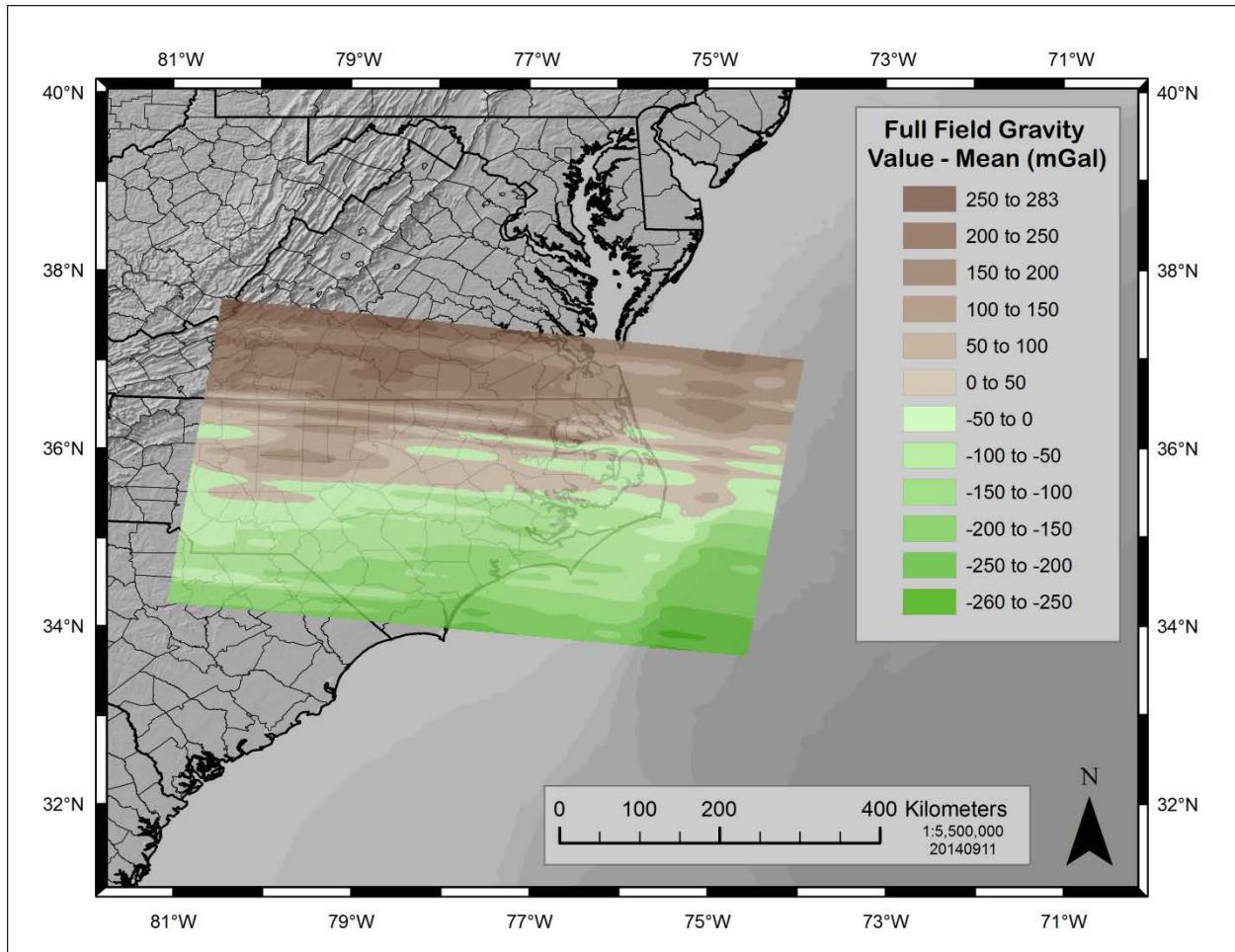


Figure 4: Full-field gravity at altitude (mean removed) for Block ES04. This is the data in the gravity release “.txt” file and includes the effects of differing altitudes along flight lines.

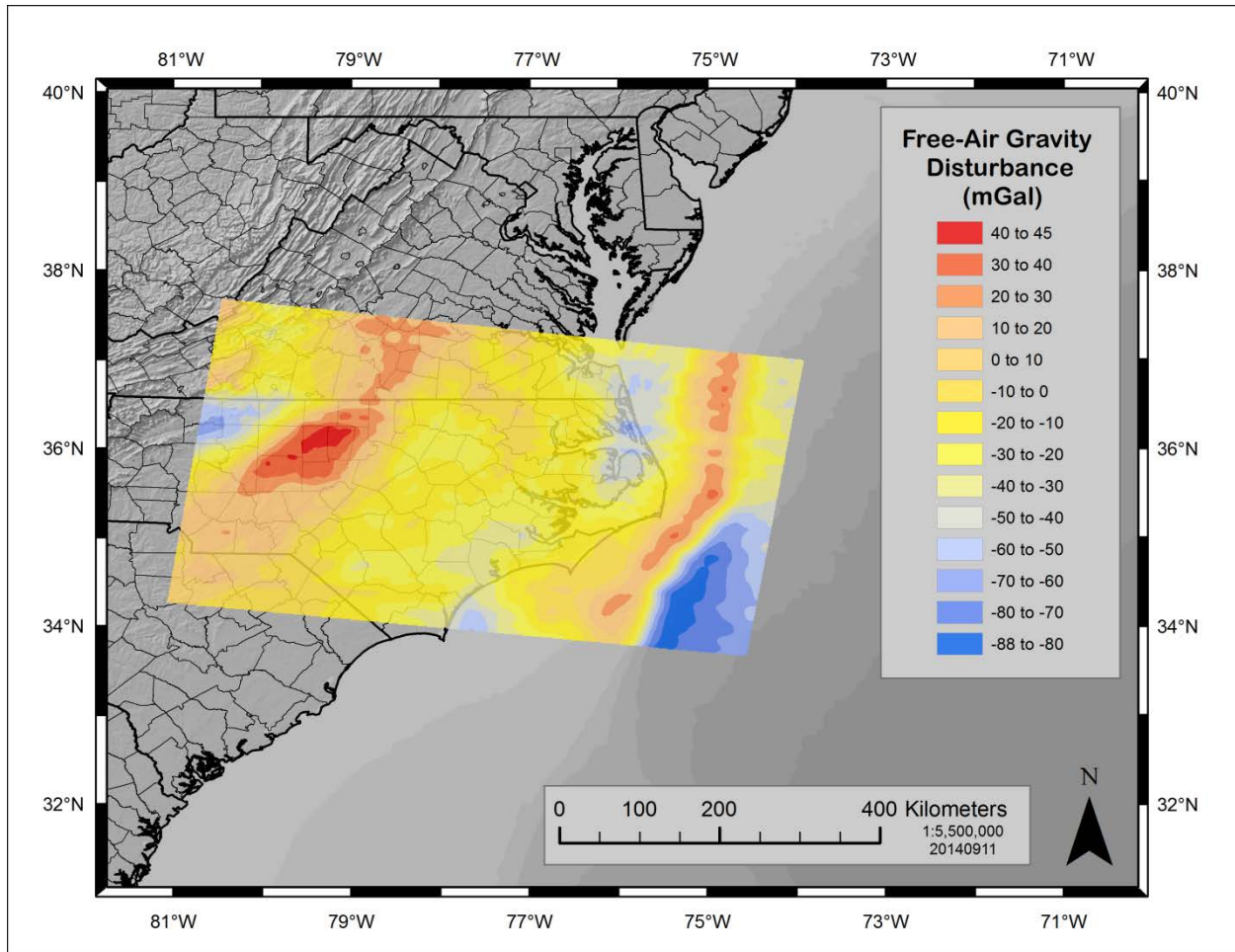


Figure 5: Free-air gravity disturbance for Block ES04 with respect to the WGS-84 ellipsoid.

4. Data Usage Guidelines

4.1 Suggested Data Handling

This data product was purposefully filtered to preserve the amplitude of the long-wavelength gravity signal. As a trade-off, the filter allows some short wavelength noise to remain in the product. Prior to use for geophysical purposes, the data should be run through a frequency-domain low-pass filter to remove that excess short wavelength noise. For geodetic purposes, higher frequencies can be damped during inclusion into a spherical harmonic model. In any case where downward continuation will be done with this data, the high frequency noise should first be filtered out, damped, or otherwise dealt with so that the downward continuation does not amplify the noise.

4.2 Documentation

The survey block User Manual, the general GRAV-D User Manual, and metadata for the block should all be downloaded with the data and kept in the same directory. The contents of the manuals are critical to correctly understanding the quality of the data and using the data properly.

4.3 How to Cite These Data

The following citations should be used in all presentations or publications that reference the GRAV-D work. Please replace the *DATE* tag in the following references with the date you downloaded the data or reports from the NGS website.

The GRAV-D Team, in alphabetical order, are: Vicki A. Childers, Justin E. Dahlberg, Theresa M. Damiani, Sandra A. Martinka Preaux, Carly A. Weil, Tim G. Wilkins, and Monica A. Youngman.

To reference the ES04 data file, reference the webpage:

GRAV-D Team (2014). "Gravity for the Redefinition of the American Vertical Datum (GRAV-D) Project, Airborne Gravity Data; Block ES04". Available *DATE*. Online at: http://www.ngs.noaa.gov/GRAV-D/data_ES04.shtml

To reference the block and survey details, reference the block user manual:

GRAV-D Team (2014). "Block ES04 (Eastern South 03); GRAV-D Airborne Gravity Data User Manual." Monica Youngman and Carly Weil, ed. Version BETA. Available *DATE*. Online at: http://www.ngs.noaa.gov/GRAV-D/data_ES04.shtml

To reference the general GRAV-D project operations, reference the General User Manual:

GRAV-D Team (2013). "GRAV-D General Airborne Gravity Data User Manual." Theresa Damiani and Monica Youngman, ed. Version 2. Available *DATE*. Online at: http://www.ngs.noaa.gov/GRAV-D/data_ES04.shtml

5. References

Micro-g LaCoste, 2010. "TAGS Turnkey Airborne Gravity System AIR III Hardware & Operations Manual."